

# Probabilistic Numerical Methods for Deterministic Differential Equations

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# Outline

1 Introduction

2 Ordinary Differential Equations

3 Elliptic PDE

4 Conclusions

# Outline

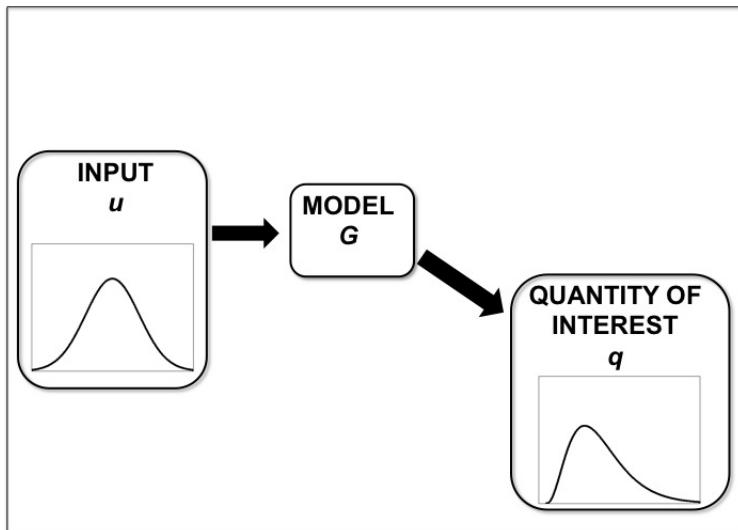
**1 Introduction**

2 Ordinary Differential Equations

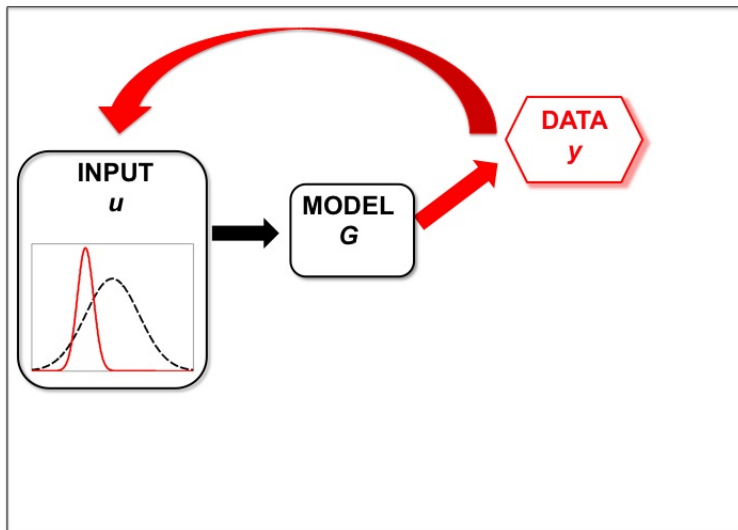
3 Elliptic PDE

4 Conclusions

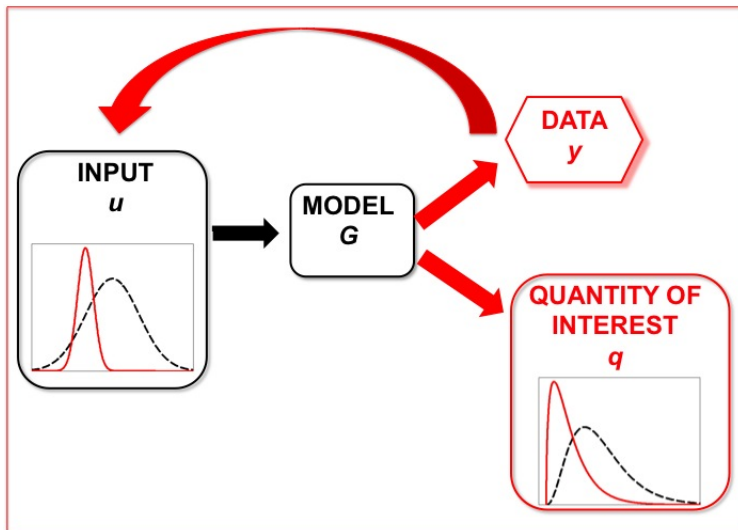
# Uncertainty Quantification (UQ)



## Bayesian Inverse Problem (BIP)



# BIP and UQ



# Deterministic Approach to Numerical Approximation of $G$

## Assumption on Numerical Integrator

Approximate forward map  $G$  by a numerical method to obtain  $G^N$ :

$$\|G(u) - G^N(u)\| \leq \psi(N) \rightarrow 0$$

as  $N \rightarrow \infty$ . Leads to approximate posterior measure  $\mu^N$  in place of  $\mu$ .

## Theorem

For appropriate class of test functions  $f : X \rightarrow S$ :

$$\|\mathbb{E}^\mu f(u) - \mathbb{E}^{\mu^N} f(u)\|_S \leq C\psi(N).$$



S.L. Cotter, M. Dashti and A. M. Stuart

Approximation of Bayesian Inverse Problems.

*SINUM* 2010 **48**(2010) 322–345.

# Probabilistic Approach to Numerical Approximation of $G$

- Approximate  $G$  by a **random** map  $G^{N,\omega}$ .
- Ensure that:  $\mathbb{E}\|G(u) - G^{N,\omega}(u)\| \leq \psi(N)$ .
- Vanilla UQ: infer scale parameter  $\sigma$  in  $G^{N,\omega}(u)$ .
- BIP UQ: augment unknown input parameters  $u$  by  $\omega$ .



## J. Skilling

Bayesian solution of ordinary differential equations  
*Maximum Entropy and Bayesian Methods 1992, 23–37.*



## O.A. Chkrebtii, D.A. Campbell, M.A. Girolami, B. Calderhead

Bayesian uncertainty quantification for differential equations  
*arxiv.1306.2365*



## M. Schober, D.K. Duvenaud and P. Hennig

Probabilistic ODE solvers with Runge- Kutta means  
*NIPS 2014, 739–747.*



## P. Conrad, M. Girolami, S. Sarkka, A.M. Stuart and K. Zygalakis

*arxiv.1506.04592*



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## Set-Up

### Consider the ODE:

$$\frac{du}{dt} = f(u), \quad u(0) = u_0.$$

### One-step numerical method

For  $U_k \approx u(kh)$ :

$$U_{k+1} = \Psi_h(U_k), \quad U_0 = u_0.$$

### Randomized numerical method

For  $U_k \approx u(kh)$ :

$$U_{k+1} = \Psi_h(U_k) + \xi_k(h), \quad U_0 = u_0,$$

where  $\xi_k(\cdot)$  is a Gaussian random field defined on  $[0, h]$ .

## Derivation (Euler)

### Integral equation

For  $u_k = u(kh)$  and for  $t \in [t_k, t_{k+1}]$ :

$$\begin{aligned}u(t) &= u_k + \int_{t_k}^{t_{k+1}} f(u(s)) ds \\ &= u_k + \int_{t_k}^t g(s) ds.\end{aligned}$$

### Uncertain $g$

We do not know  $g(s)$ . Assume that  $g$  is a Gaussian random field conditioned to satisfy  $g(t_k) = f(U_k)$ . This gives approximation  $U(t)$  for  $t \in [t_k, t_{k+1}]$ :

$$\begin{aligned}U(t) &= U_k + (t - t_k)f(U_k) + \xi_k(t - t_k). \\ U_{k+1} &= U_k + hf(U_k) + \xi_k(h).\end{aligned}$$

# Assumptions

## Assumption 1

Let  $\xi(t) := \int_0^t \chi(s) ds$  with  $\chi \sim N(0, C^h)$ . Then there exists  $K > 0, p \geq 1$  such that, for all  $t \in [0, h]$ ,  $\mathbf{E}|\xi(t)\xi(t)^T|_{\mathbb{F}}^2 \leq Kt^{2p+1}$ ; in particular  $\mathbf{E}|\xi(t)|^2 \leq Kt^{2p+1}$ . Furthermore we assume the existence of matrix  $Q$ , independent of  $h$ , such that  $\mathbf{E}\xi(h)\xi(h)^T = Qh^{2p+1}$ .

## Assumption 2

The function  $f$  and a sufficient number of its derivatives are bounded uniformly in  $\mathbf{R}^n$  in order to ensure that  $f$  is globally Lipschitz and that the numerical flow-map  $\Psi_h$  has uniform local truncation error of order  $q + 1$  with respect to the true flow-map  $\Phi_h$ :

$$\sup_{u \in \mathbf{R}^n} |\Psi_t(u) - \Phi_t(u)| \leq Kt^{q+1}.$$

## Theorem

### Theorem

Under Assumptions 1 and 2 it follows that there is  $K > 0$  such that

$$\sup_{0 \leq kh \leq T} \mathbf{E}|u_k - U_k|^2 \leq Kh^{2 \min\{p, q\}}.$$

Furthermore

$$\sup_{0 \leq t \leq T} \mathbf{E}|(u(t) - U(t))| \leq Kh^{\min\{p, q\}}.$$

### Scaling of Noise

- Optimal scaling of noise is  $p = q$ .
- Then deterministic rate of convergence is unaffected.
- But maximal noise is added to the system.
- Fit constant  $\sigma$  in scale matrix  $Q = \sigma I$  to an error estimator.

## ODE Example

### FitzHugh-Nagumo Model

We illustrate the randomized ODE solvers on the FitzHugh-Nagumo model two-species  $(V, R)$  non-linear oscillator, with parameters  $(a, b, c)$ .

### Governing Equations

$$\frac{dV}{dt} = c \left( V - \frac{V^3}{3} + R \right), \quad (1)$$

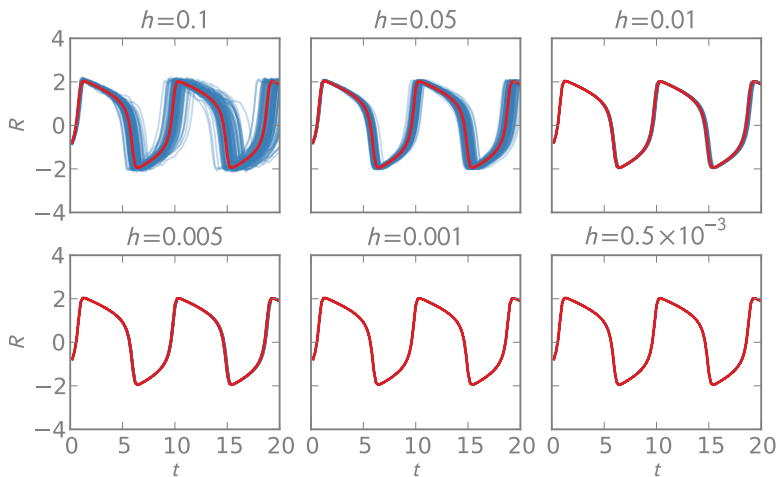
$$\frac{dR}{dt} = -\frac{1}{c} (V - a + bR). \quad (2)$$

### Parameter Values

For numerical results, we choose fixed initial conditions  $V(0) = -1, R(0) = 1$ , and parameter values  $(.2, .2, 3)$ .

# Convergence of Random Solutions

Draws from the random solver for fixed  $\sigma$



# Backward Error Analysis

## Modified (Stochastic Differential) Equation

$$\frac{du^h}{dt} = f(u^h) + h^q \sum_{l=0}^q h^l f_l(u^h) + \sqrt{Qh^{2q}} \frac{dW}{dt}, \quad u^h(0) = u_0$$

## Theorem

Under Assumptions 1 and 2, for  $\Phi$  a  $C^\infty$  function with all derivatives bounded uniformly on  $\mathbf{R}^n$ , there is a choice of  $\{f_\ell\}_{\ell=0}^q$  such that weak error for true equation is given by

$$\left| \Phi(u(T)) - \mathbf{E}\Phi(U_k) \right| \leq Kh^q, \quad kh = T.$$

whilst weak error from the modified equation is given by

$$\left| \mathbf{E}\Phi(u^h(T)) - \mathbf{E}\Phi(U_k) \right| \leq Kh^{2q+1}, \quad kh = T.$$



## Statistical Inference: find $\theta = (a, b, c)$ from noisy observations

### Inverse Problem

$$y_j = u(t_j) + \eta_j, \quad y = \mathcal{G}(\theta) + \eta.$$

### Deterministic Solver

Simply replace  $u(\cdot)$  by deterministic approximation to obtain

$$y = \mathcal{G}^h(\theta) + \eta.$$

Use MCMC to compute  $\mathbb{P}(\theta|y)$ .

### Randomized Solver

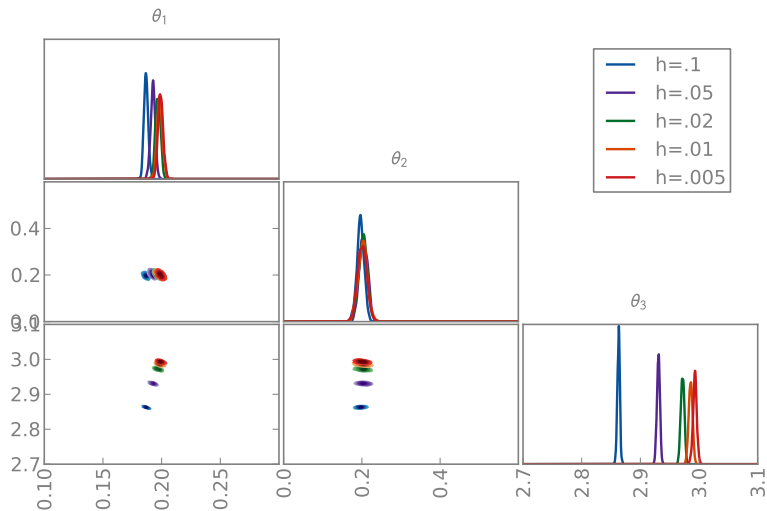
Replace  $u(\cdot)$  by random approximation to obtain

$$y = \mathcal{G}^h(\theta, \xi) + \eta.$$

Use MCMC to compute  $\int \mathbb{P}(\theta, \xi|y) d\xi$ .

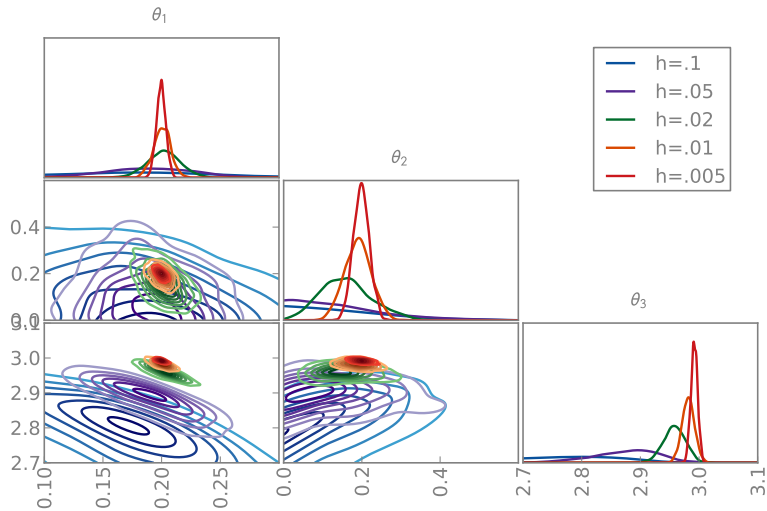
# FitzHugh-Nagumo Parameter Posterior (Deterministic Solver)

Posterior is over-confident at finite  $h$  values



# FitzHugh-Nagumo Parameter Posterior (Random Solver)

Posterior still contains bias, but posterior width reflects error



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## Set-Up

### Weak Form

$$u \in \mathcal{V} : a(u, v) = r(v), \quad \forall v \in \mathcal{V}.$$

### Galerkin Method

$$u^h \in \mathcal{V}^h : a(u^h, v) = r(v), \quad \forall v \in \mathcal{V}^h.$$

Then

$$\mathcal{V}^h = \text{span}\{\Phi_j = \Phi_j^s\}_{j=1}^J.$$

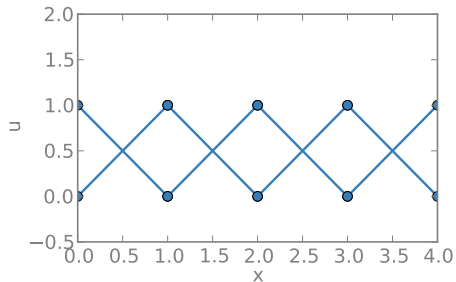
### Randomized Galerkin Method

$\mathcal{V}^h$  comprises small randomized perturbations of the standard Galerkin method:

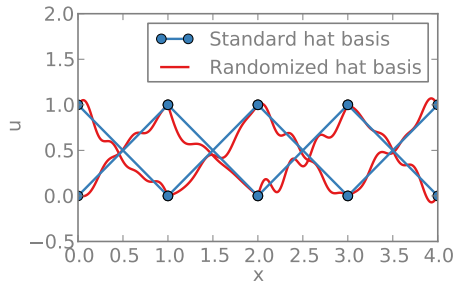
$$\mathcal{V}^h = \text{span}\{\Phi_j = \Phi_j^s + \Phi_j^r\}_{j=1}^J.$$

# Derivation

## Standard basis



## Randomized basis



## Assumptions

### Assumption 1

The  $\{\Phi_j^r\}_{j=1}^J$  are independent, mean zero, Gaussian random fields, with the same support as the  $\{\Phi_j^s\}$ , and satisfying

$$\Phi_j^r(x_k) = 0 \quad \forall \{j, k\}, \quad \sum_{j=1}^J \mathbf{E} \|\Phi_j^r\|_a^2 \leq Ch^{2q}.$$

### Assumption 2

The true solution  $u$  is in  $L^\infty(D)$ . Furthermore the standard deterministic interpolant of the true solution, defined by

$$v^s := \sum_{j=1}^J u(x_j) \Phi_j^s,$$

satisfies  $\|u - v^s\|_a \leq Ch^p$ .

## Theorem

### Theorem

Under Assumptions 1 and 2 it follows that the random approximation  $u^h$  satisfies

$$\mathbf{E}\|u - u^h\|_a^2 \leq Ch^{2\min\{p,q\}}.$$

### Corollary (Aubin-Nitsche Duality)

Consider the Poisson equation with Dirichlet boundary conditions and a random perturbation of the piecewise linear FEM approximation, with  $p = q = 1$ . Under Assumptions 1 and 2 it follows that the random approximation  $u^h$  satisfies

$$\mathbf{E}\|u - u^h\|_{L^2} \leq Ch^2.$$

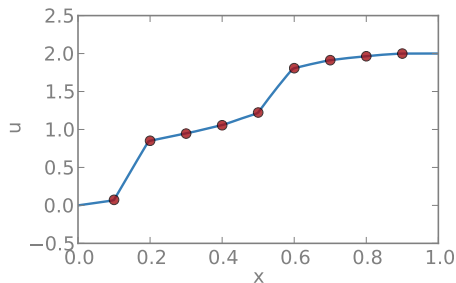
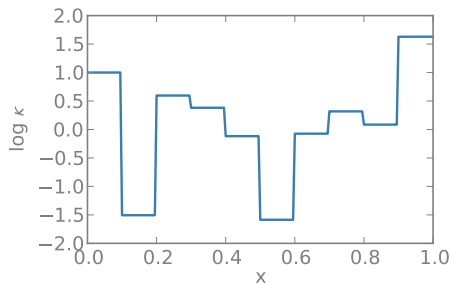


## PDE Example

Standard elliptic inversion problem:

$$-\nabla \cdot (\kappa(x) \nabla u(x)) = -4x$$

$$u(0) = 0, u(1) = 2$$



$$\kappa(x) = \sum_{n=1}^N \theta_i \mathbb{I}_i(x).$$

# Statistical Inference: find $\theta$ from noisy observations

## Inverse Problem

$$y_j = u(t_j) + \eta_j, \quad y = \mathcal{G}(\theta) + \eta.$$

## Deterministic Solver

Simply replace  $u(\cdot)$  by deterministic approximation to obtain

$$y = \mathcal{G}^h(\theta) + \eta.$$

Use MCMC to compute  $\mathbb{P}(\theta|y)$ .

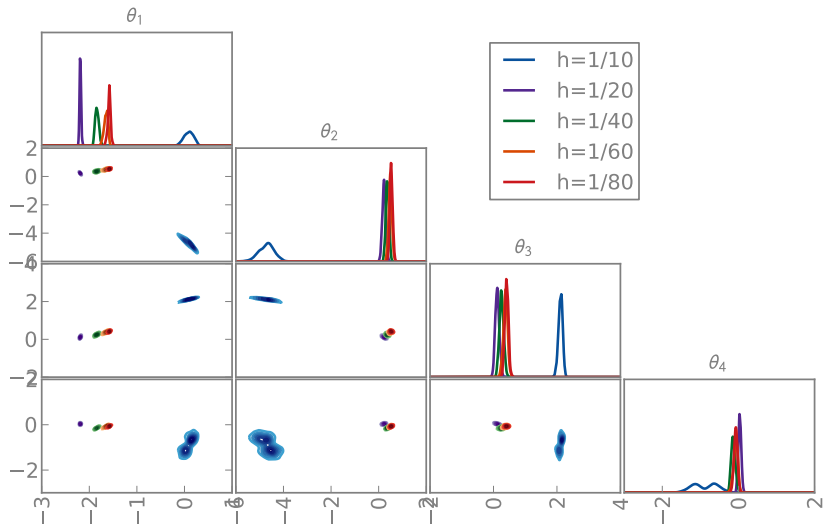
## Randomized Solver

Replace  $u(\cdot)$  by random approximation to obtain

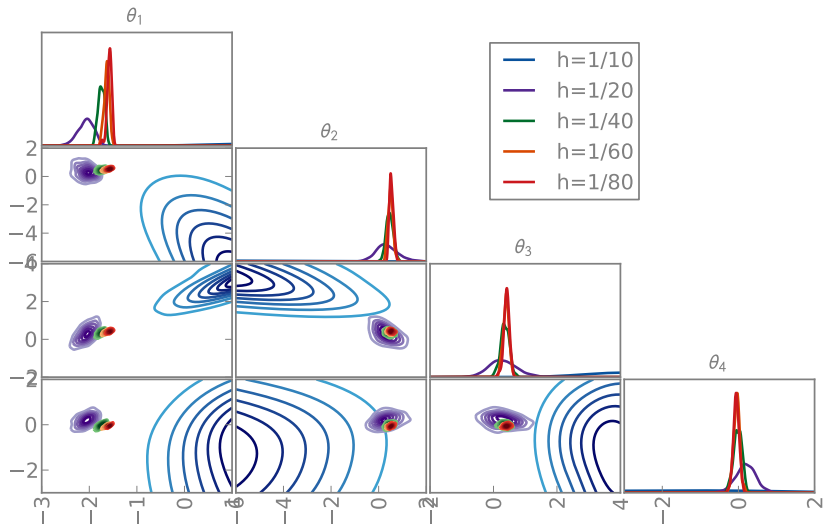
$$y = \mathcal{G}^h(\theta, \xi) + \eta.$$

Use MCMC to compute  $\int \mathbb{P}(\theta, \xi|y) d\xi$ .

# Elliptic Inference (Deterministic Solver)



# Elliptic Inference (Random Solver)



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## Summary

- Numerical methods are inherently uncertain.
- Classical numerical analysis upper bounds this uncertainty.
- Our approach treats it as a random variable.
- Mean square rates of convergence are derived, consistent with classical numerical analysis.
- Backward error analysis gives universal interpretation of the methods as solving stochastic or random problems.
- In forward modelling scale parameter is set using classical error indicators.
- In inverse modelling, the random parameters augment the unknown inputs.

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arxiv.1506.04592