An adaptive sparse grid algorithm for elliptic PDEs with lognormal diffusion coefficient

F. Nobile<sup>†</sup>, L. Tamellini<sup>†</sup>, R. Tempone<sup> $\flat$ </sup>, F. Tesei<sup>†</sup>

<sup>†</sup> CSQI - MATHICSE, EPFL, Switzerland
 <sup>b</sup> SRI UQ Center, KAUST, Saudi Arabia

Swiss Numerical Analysis Day 2015 Genève, April 17, 2015

#### Outline



- 2 The lognormal Darcy problem
- 3 Adaptive sparse grids
- 4 Monte Carlo Control Variate

#### Outline

#### 1 Uncertainty Quantification

- 2 The lognormal Darcy problem
- 3 Adaptive sparse grids
- 4 Monte Carlo Control Variate

$$\begin{array}{ccc} \text{math. model} \\ \mathcal{P}(\text{state vars.}) = 0 \end{array} \xrightarrow{\phantom{aaaaaa}} \begin{array}{c} \text{quantity of} \\ \text{interest } u \end{array}$$



$$\begin{array}{ccc} \mathsf{parameters} & \to & \mathsf{math. model} \\ \mathbf{y} & \to & \mathcal{P}(\mathsf{state vars.}, \mathbf{y}) = \mathbf{0} & \to & \mathsf{quantity of} \\ \end{array}$$

• The parameters **y** of the model may be *affected by uncertainty* (experimental measures, limited knowledge on system properties).

$$\begin{array}{ccc} \mathsf{parameters} & \to & \mathsf{math. model} \\ \mathbf{y} & \to & \mathcal{P}(\mathsf{state vars.}, \mathbf{y}) = \mathbf{0} & \to & \mathsf{interest} \ u(\mathbf{y}) \end{array}$$

- The parameters **y** of the model may be *affected by uncertainty* (experimental measures, limited knowledge on system properties).
- **y** can be modeled as a **random vector** with *N* components, taking values in  $\Gamma \subseteq \mathbb{R}^N$ , with joint probability density function  $\varrho(\mathbf{y})$ .

#### Therefore u is a **random function**, $u(\mathbf{y})$ .

**Goal:** Compute statistical quantities for u, i.e. assess how the uncertainty on the parameters reflects on u:  $\mathbb{E}[u]$ ,  $\mathbb{Var}[u]$ ,  $Pr(u > u_0)$ .

**Method:** Use sparse grids collocation to exploit regularity of  $u(\mathbf{y})$ .

#### Some examples on what can be done

Diffusion problem with random inclusions ("the cookies problem")



#### Some examples on what can be done

Steady Navier-Stokes with uncertain Reynolds and forcing term





#### Outline





- 3 Adaptive sparse grids
- 4 Monte Carlo Control Variate

#### The Darcy problem

Find a pressure 
$$p: \overline{D} \to \mathbb{R}$$
, such that  

$$\begin{cases}
-\nabla \cdot (e^{\gamma} \nabla p) = f & \text{in } D, \\
+B.C. \text{ (see plot on the right).} \\
u = \text{outward flux from the right-hand boundary.} \\
\end{cases}$$

$$(e^{\gamma} \nabla p) \cdot \mathbf{n} = 0$$

$$(e^{\gamma} \nabla p) \cdot \mathbf{n} = 0$$

the log-permeability field  $\gamma$  is not constant in space (see right) but in practice we know its value only at log-points (drill locations). How to fill the gaps?



model  $\gamma$  as a random field

1

#### Random fields

- instead of  $\gamma = \gamma(\mathbf{x})$ , let  $\gamma = \gamma(\mathbf{x}, \mathbf{y})$  with  $y_n$  random variables,  $\mathbf{y} \in \Gamma$ :
  - for each realization  $\gamma(\cdot, \mathbf{y})$  is a function in  $L^{\infty}(D)$
  - for each physical point  $\gamma(\mathbf{x}, \cdot)$  is a random variable
- a covariance function describes the interaction between any couple of points, e.g.  $Cov [\mathbf{x}_0, \mathbf{x}_1] = \exp\left(-\frac{\|\mathbf{x}_0 \mathbf{x}_1\|^2}{L_c^2}\right)$
- represented by a (truncated) Karhunen-Loève expansion

$$\gamma(\mathbf{x}, \mathbf{y}) = \sigma \sum_{k=1}^{N} y_k \gamma_k \phi_k(\mathbf{x}), \quad y_i \sim \mathcal{N}(0, 1) \text{ i.i.d.} \Rightarrow \begin{cases} \mathsf{\Gamma} = \mathbb{R}^N \\ \varrho(\mathbf{y}) = \frac{1}{\sqrt{(2\pi)^N}} e^{-\frac{\sum_{n=1}^N y_n^2}{2}} \end{cases}$$

Find a pressure  $p(\mathbf{x}, \mathbf{y}) : \overline{D} \times \Gamma \to \mathbb{R}$ , such that  $\varrho$ -a.e.:

$$\begin{cases} -\nabla \cdot (e^{\gamma(\mathbf{x},\mathbf{y})} \nabla p(\mathbf{x},\mathbf{y})) = f(\mathbf{x}) \quad \mathbf{x} \in D, \\ +B.C. \end{cases}$$

 $u(\mathbf{y}) =$ outward flux is a random fun. $\rightarrow$  approximate e.g.  $\mathbb{E}[u]$ 

#### What strategy?

**Problem:** we may need **tens-hundreds of random variables** to represent accurately the field! How can we tackle this?

#### Monte Carlo

• Generate a sample  $\{\mathbf{y}_i\}_{i=1}^M$ 

• 
$$\mathbb{E}[u] \approx u_{MC} = \frac{1}{M} \sum_{i} u(\mathbf{y}_i)$$

 accuracy O(1/√M). Slow but independent of N (no "curse of dimensionality")

#### **Polynomial approximation**

- The map y → u(x, y) is actually very smooth
- Approximate it by a polynomial surrogate model,
   u(y) ≈ u<sub>pol</sub> = ∑<sub>i</sub> u<sub>i</sub>φ<sub>i</sub>(y)
- $\mathbb{E}[u_{pol}]$  by post-process
- convergence of  $\|u u_{pol}\|$  may deteriorate with N

In this talk: Polynomial approximation by adaptive sparse grids (reduced "curse of dimensionality") + Monte Carlo with control variate

#### Lorenzo Tamellini (EPFL)

#### Outline

1 Uncertainty Quantification

- 2 The lognormal Darcy problem
- 3 Adaptive sparse grids
  - 4 Monte Carlo Control Variate

## Sparse grid approximation of $u(\mathbf{y})$

Let  $\mathbf{i} \in \mathbb{N}^N_+$  and denote by  $\mathcal{T}^{m(\mathbf{i})}[u](\mathbf{y})$  the tensor Lagrangian interpolant of  $u(\mathbf{y})$  over  $\Gamma$  with  $m(i_1) \times m(i_1) \times \dots m(i_N)$  points.

A sparse grid approximation is a linear combination of tensor interpolants:



In practice, solve the Darcy problem for each  $\mathbf{y}_i$  in the grid and combine them according to the formula above

## Sparse grid approximation of $u(\mathbf{y})$

Let  $\mathbf{i} \in \mathbb{N}^N_+$  and denote by  $\mathcal{T}^{m(\mathbf{i})}[u](\mathbf{y})$  the tensor Lagrangian interpolant of  $u(\mathbf{y})$  over  $\Gamma$  with  $m(i_1) \times m(i_1) \times \dots m(i_N)$  points.

A sparse grid approximation is a linear combination of tensor interpolants:

$$\mathcal{S}_{\mathcal{I}}[u](\mathbf{y}) := \sum_{\mathbf{i} \in \mathcal{I}} c_{\mathbf{i}} \mathcal{T}^{m(\mathbf{i})}[u](\mathbf{y}), \qquad \mathbb{E}[u] \approx \mathcal{Q}_{\mathcal{I}}[u] := \sum_{\mathbf{y}_{i}} \omega_{i} u(\mathbf{y}_{i})$$

- Sparse grids idea: cheaper than full tensor grids, but similar accuracy
- Univariate points:  $y_i \sim \mathcal{N}(0,1) \rightarrow \text{Gauss-Hermite, Genz-Keister,}$  gen. Leja
- The efficiency of the sparse grids depends on  $\ensuremath{\mathcal{I}}.$
- Admissibility condition for  $\mathcal{I}$ :  $\forall \mathbf{i} \in \mathcal{I}, \quad \mathbf{i} \mathbf{e}_j \in \mathcal{I} \text{ if } i_j > 1.$
- The coefficients  $c_i$  are uniquely defined given  $\mathcal{I}$



Given  $\mathbf{i} = \mathbf{1}$ ,  $\mathcal{I} = {\mathbf{i}}$  and  $\mathcal{R} = \emptyset$  repeat:

- $\textcircled{0} \quad \mathsf{Add} \text{ to } \mathcal{R} \text{ the neighbors of } \mathbf{i} \text{ feasible wrt to } \mathcal{I}$
- **2** Compute  $S_{\mathcal{I}\cup\mathcal{B}}[u]$
- If find the index j ∈ R that improved the most the approximation (e.g. check the difference in approximation of the mean or in L<sup>∞</sup>-norm)
- set  $\mathbf{i} = \mathbf{j}$  and move it from  $\mathcal{R}$  to  $\mathcal{I}$

NB: omitting technicalities using non-nested points and unbounded  $\boldsymbol{\Gamma}.$ 



Given  $\mathbf{i} = \mathbf{1}$ ,  $\mathcal{I} = {\mathbf{i}}$  and  $\mathcal{R} = \emptyset$  repeat:

- $\textcircled{0} \ \ \, \text{Add to } \mathcal{R} \ \, \text{the neighbors of } \mathbf{i} \ \, \text{feasible wrt to } \mathcal{I}$
- **2** Compute  $S_{\mathcal{I}\cup\mathcal{B}}[u]$
- If ind the index j ∈ R that improved the most the approximation (e.g. check the difference in approximation of the mean or in L<sup>∞</sup>-norm)
- set  $\mathbf{i} = \mathbf{j}$  and move it from  $\mathcal{R}$  to  $\mathcal{I}$

NB: omitting technicalities using non-nested points and unbounded  $\boldsymbol{\Gamma}.$ 



Given  $\mathbf{i} = \mathbf{1}$ ,  $\mathcal{I} = {\mathbf{i}}$  and  $\mathcal{R} = \emptyset$  repeat:

- $\textcircled{0} \quad \mathsf{Add} \text{ to } \mathcal{R} \text{ the neighbors of } \mathbf{i} \text{ feasible wrt to } \mathcal{I}$
- **2** Compute  $S_{\mathcal{I}\cup\mathcal{B}}[u]$
- If find the index j ∈ R that improved the most the approximation (e.g. check the difference in approximation of the mean or in L<sup>∞</sup>-norm)
- set  $\mathbf{i} = \mathbf{j}$  and move it from  $\mathcal{R}$  to  $\mathcal{I}$

NB: omitting technicalities using non-nested points and unbounded  $\boldsymbol{\Gamma}.$ 



Given  $\mathbf{i} = \mathbf{1}$ ,  $\mathcal{I} = {\mathbf{i}}$  and  $\mathcal{R} = \emptyset$  repeat:

- $\textcircled{0} \quad \text{Add to } \mathcal{R} \text{ the neighbors of } \mathbf{i} \text{ feasible wrt to } \mathcal{I}$
- **2** Compute  $S_{\mathcal{I}\cup\mathcal{B}}[u]$
- If ind the index j ∈ R that improved the most the approximation (e.g. check the difference in approximation of the mean or in L<sup>∞</sup>-norm)
- **④** set  $\mathbf{i} = \mathbf{j}$  and move it from  $\mathcal{R}$  to  $\mathcal{I}$

NB: omitting technicalities using non-nested points and unbounded  $\Gamma$ .



Given  $\mathbf{i} = \mathbf{1}$ ,  $\mathcal{I} = {\mathbf{i}}$  and  $\mathcal{R} = \emptyset$  repeat:

- $\textcircled{0} \quad \text{Add to } \mathcal{R} \text{ the neighbors of } \mathbf{i} \text{ feasible wrt to } \mathcal{I}$
- **2** Compute  $S_{\mathcal{I}\cup\mathcal{B}}[u]$
- If ind the index j ∈ R that improved the most the approximation (e.g. check the difference in approximation of the mean or in L<sup>∞</sup>-norm)
- **④** set  $\mathbf{i} = \mathbf{j}$  and move it from  $\mathcal{R}$  to  $\mathcal{I}$

NB: omitting technicalities using non-nested points and unbounded  $\Gamma$ .

Lorenzo Tamellini (EPFL)



Given  $\mathbf{i} = \mathbf{1}$ ,  $\mathcal{I} = {\mathbf{i}}$  and  $\mathcal{R} = \emptyset$  repeat:

- **2** Compute  $S_{\mathcal{I}\cup\mathcal{B}}[u]$
- If ind the index j ∈ R that improved the most the approximation (e.g. check the difference in approximation of the mean or in L<sup>∞</sup>-norm)
- **④** set  $\mathbf{i} = \mathbf{j}$  and move it from  $\mathcal{R}$  to  $\mathcal{I}$

NB: omitting technicalities using non-nested points and unbounded  $\Gamma$ .

 $\bullet$  Problem: generating  ${\cal R}$  in high-dimensional spaces is too expensive.

- **Problem:** generating  $\mathcal{R}$  in high-dimensional spaces is too expensive.
- Assume that the Karhunen–Loève expansion  $\gamma = \sigma \sum_{k=1}^{N} y_k \gamma_k \phi_k$ introduces a "weak ordering" of random variables, i.e. there exists  $N_b \ge 1$  (buffer) s.t.  $y_{n+N_b}$  is guaranteed to be less important than  $y_n$ .

- **Problem:** generating  $\mathcal{R}$  in high-dimensional spaces is too expensive.
- Assume that the Karhunen–Loève expansion  $\gamma = \sigma \sum_{k=1}^{N} y_k \gamma_k \phi_k$ introduces a "weak ordering" of random variables, i.e. there exists  $N_b \ge 1$  (buffer) s.t.  $y_{n+N_b}$  is guaranteed to be less important than  $y_n$ .
- Idea: Add random variables gradually (balance refinement and addition of variables). Note that this means we don't need to truncate a-priori the Karhunen–Loève expansion of γ!

- **Problem:** generating  $\mathcal{R}$  in high-dimensional spaces is too expensive.
- Assume that the Karhunen–Loève expansion  $\gamma = \sigma \sum_{k=1}^{N} y_k \gamma_k \phi_k$ introduces a "weak ordering" of random variables, i.e. there exists  $N_b \ge 1$  (buffer) s.t.  $y_{n+N_b}$  is guaranteed to be less important than  $y_n$ .
- Idea: Add random variables gradually (balance refinement and addition of variables). Note that this means we don't need to truncate a-priori the Karhunen–Loève expansion of γ!
- **Define** a random variable  $y_n$  as **activated** if  $\min_{i \in \mathcal{I}} i_n > 1$ .

- Problem: generating  $\mathcal{R}$  in high-dimensional spaces is too expensive.
- Assume that the Karhunen–Loève expansion  $\gamma = \sigma \sum_{k=1}^{N} y_k \gamma_k \phi_k$ introduces a "weak ordering" of random variables, i.e. there exists  $N_b \ge 1$  (buffer) s.t.  $y_{n+N_b}$  is guaranteed to be less important than  $y_n$ .
- Idea: Add random variables gradually (balance refinement and addition of variables). Note that this means we don't need to truncate a-priori the Karhunen–Loève expansion of γ!
- **Define** a random variable  $y_n$  as **activated** if  $\min_{i \in I} i_n > 1$ .

A simple dimension-adaptive algorithm

- start the adaptive algorithm using  $N_b$  random variables
- As soon as one of these "buffer variables" gets activated, add a new random variable to the approximaton.

#### The uncertain Darcy problem – results 1 Field data: $\sigma = 1$ , corr. length $L_c = 0.5$ , $\gamma(\mathbf{x}, \mathbf{y})$ smooth wrt $\mathbf{x}$



- moderate number of random variables needed
- convergence robust wrt. type of points and  $\mathbb{E}[]/L^\infty\text{-driven}$  adaptation

#### **Smoothness Warning!**

If  $\gamma(\mathbf{x}, \mathbf{y})$  is not smooth wrt  $\mathbf{x}$  (depends on the covariance function), a larger number of random variables is needed and even the adaptive sparse grids may not be effective!

#### Outline

1 Uncertainty Quantification

- 2 The lognormal Darcy problem
- 3 Adaptive sparse grids
- 4 Monte Carlo Control Variate

# Rough random fields $\gamma$ : Monte Carlo Control Variate $\gamma$ non-differentiable wrt $\mathbf{x} \Rightarrow$ sparse grids may be non-effective.

Remedy: use sparse grids as control var. (preconditioner) for MC

• Consider a smoothed field  $\gamma^{\epsilon}$ , such that  $\mathcal{Q}_{\mathcal{I}}[u^{\epsilon}] \to \mathbb{E}[u^{\epsilon}]$  quickly.



#### Rough random fields $\gamma$ : Monte Carlo Control Variate

 $\gamma$  non-differentiable wrt  $\mathbf{x} \Rightarrow$  sparse grids may be non-effective.

Remedy: use sparse grids as control var. (preconditioner) for MC

- Consider a smoothed field  $\gamma^{\epsilon}$ , such that  $\mathcal{Q}_{\mathcal{I}}[u^{\epsilon}] \to \mathbb{E}[u^{\epsilon}]$  quickly.
- **2** Define  $u_{CV} = u u^{\epsilon} + Q_{\mathcal{I}}[u^{\epsilon}]$ . There holds

 $\mathbb{E}[u_{CV}] = \mathbb{E}[u], \quad \mathbb{V}ar(u_{CV}) = \mathbb{V}ar(u) + \mathbb{V}ar(u^{\epsilon}) - 2cov(u, u^{\epsilon})$ 

Thus, the smaller  $\epsilon$ , the smaller the MC error, but slower the convergence  $\mathcal{Q}_{\mathcal{I}}[u^{\epsilon}] \to \mathbb{E}[u^{\epsilon}]$ .

#### Rough random fields $\gamma$ : Monte Carlo Control Variate

 $\gamma$  non-differentiable wrt  $\mathbf{x} \Rightarrow$  sparse grids may be non-effective.

Remedy: use sparse grids as control var. (preconditioner) for MC

- Consider a smoothed field  $\gamma^{\epsilon}$ , such that  $\mathcal{Q}_{\mathcal{I}}[u^{\epsilon}] \to \mathbb{E}[u^{\epsilon}]$  quickly.
- **2** Define  $u_{CV} = u u^{\epsilon} + Q_{\mathcal{I}}[u^{\epsilon}]$ . There holds

 $\mathbb{E}[u_{CV}] = \mathbb{E}[u], \quad \mathbb{V}ar(u_{CV}) = \mathbb{V}ar(u) + \mathbb{V}ar(u^{\epsilon}) - 2cov(u, u^{\epsilon})$ 

Thus, the smaller  $\epsilon$ , the smaller the MC error, but slower the convergence  $\mathcal{Q}_{\mathcal{I}}[u^{\epsilon}] \to \mathbb{E}[u^{\epsilon}]$ .

• Set 
$$\mathbb{E}[u_{CV}] \approx \frac{1}{M} \sum_{i=1}^{M} u^{CV}(\omega_i) = \frac{1}{M} \sum_{i=1}^{M} (u(\omega_i) - u^{\epsilon}(\omega_i)) + \mathcal{Q}_{\mathcal{I}}^m[u^{\epsilon}].$$

Here we simply choose  $M = card(pts(\mathcal{S}_{\mathcal{I}}[u]))$  (work balance). Other strategies are possible.

#### The uncertain Darcy problem - results 2

**Field data:**  $\sigma = 1$ , corr. length  $L_c = 0.5$ , rough field realizations (Hölder continuous only)



#### Conclusions

- Uncertainty Quantification is a fast-growing area at the interface between Scientific Computing and Statistics;
- Whenever the quantity of interest is smooth wrt the random parameters, adaptive sparse grids schemes can be used as an effective alternative to the Monte Carlo strategy;
- The dimension-adaptive implementation allows to work without a-priori truncation of the random field;
- If the random field has rough realizations, using adaptive sparse grids in a Monte Carlo Control Variate framework can improve results.

## Thank you for your attention!

## Thank you for your attention!



Make sure to attend

**SIAM-UQ 2016** 

#### April 5-8, 2016

SwissTech Convention Center EPFL, Lausanne, Switzerland



## Bibliography

- F. Nobile, L. Tamellini, F. Tesei and R. Tempone. An adaptive sparse grid algorithm for elliptic PDEs with lognormal diffusion coefficient. Mathicse report 4/2015, EPFL, 2015.
- F. Tesei and F. Nobile. A Multi Level Monte Carlo Method with Control Variate for elliptic PDEs with log-normal coefficients. Mathicse report 49/2014, EPFL, 2014.

F. Nobile, L. Tamellini, and R. Tempone. Convergence of quasi-optimal sparse grids approximation of Hilbert-valued functions: application to random elliptic PDEs. Mathicse report 12/2014, EPFL, 2014.

- L. Tamellini, O. Le Maître, A. Nouy Model Reduction Based on Proper Generalized Decomposition for the Stochastic Steady Incompressible Navier–Stokes Equations. SIAM Journal on Scientific Computing 36(3), 2014
- J. Beck, F. Nobile, L. Tamellini, and R. Tempone. A Quasi-optimal Sparse Grids Procedure for Groundwater Flows. Selected papers from the ICOSAHOM '12 conference.
- J. Bäck, F. Nobile, L. Tamellini, and R. Tempone. Stochastic spectral Galerkin and collocation methods for PDEs with random coefficients: a numerical comparison. Selected papers from the ICOSAHOM '09 conference.